

# **AW-XM632-SURX**

**IEEE 802.11 a/b/g/n/ac/ax Wi-Fi 6E  
+ Bluetooth 5.3 Combo Module**

## **Datasheet**

**Rev.A**

**DF**

**(For Standard)**

## Features

### Wi-Fi

- 802.11a/b/g/n/ac/ax compliant, tri-band capable (2.4/5/6 GHz).
- 5/6 GHz: 20/40/80-MHz channels, 1024-QAM, 1x1 providing up to 600 Mbps PHY data rate.
- 2.4 GHz: 20/40[1]-MHz channels, 1024-QAM, 1x1 providing up to 287 Mbps PHY data rate.
- 802.11ax STA mode and Soft AP mode with 11ax scheduled access.
- Supports 802.11d, h, k, r, v, w, ai.
- On-chip power amplifiers and low-noise amplifiers.
- Supports multipoint external coexistence interface to optimize bandwidth utilization with other co-located wireless technologies such as LTE.
- Fast VSDB (Virtual Simultaneous Dual Band).
- Worldwide regulatory support: Global products supported with worldwide homologated design.
- Integrated Arm® Cortex® R4 processor with tightly coupled memory for complete WLAN subsystem functionality. This architecture offloads the host processor completely from WLAN functionality.
- Transmission and reception of HE-SU and HE-ER-SU PPDU.
- Reception of HE-MU PPDU-OFDMA/MU-MIMO Frame.
- Transmission of HE-TB PPDU (Uplink MU OFDMA).

### Bluetooth

- Bluetooth 5.3 (BDR + EDR + BLE).
- All Bluetooth 5.0/5.1/5.2 optional features supported including LE-Audio.
- Dedicated Bluetooth® RF path for best Wi-Fi + Bluetooth coexistence performance.

- Bluetooth Class 1 or Class 2 transmitter operation.
- Supports extended synchronous connections (eSCO), for enhanced voice quality by allowing for retransmission of dropped packets.
- Adaptive frequency hopping (AFH) for reducing radio frequency interference.
- Interface support, host controller interface (HCI) using a high-speed UART interface and PCM/I2S for audio data.
- Supports multiple simultaneous Advanced Audio Distribution Profiles (A2DP) for stereo sound.
- On-chip memory includes 512 KB SRAM and 2 MB ROM.

### Interface

- SDIO 2.0/3.0 for WLAN.
- HCI-UART, PCM/I2S for Bluetooth.

### Coexistence

- Built-in advanced algorithms for Wi-Fi + Bluetooth coexistence.
- 2-wire SECI for external 3rd party Bluetooth®/GPS/LTE radios.

### General

- Fully integrated programmable dynamic Power Management Unit.
- Supports 1.8 V VDDIO.
- Supports 1340 Bytes of OTP shared between Bluetooth and WLAN for storing board parameters.



AzureWave Technologies, Inc.

## Revision History

Document NO: R2-2661-DST-02

[illegible]

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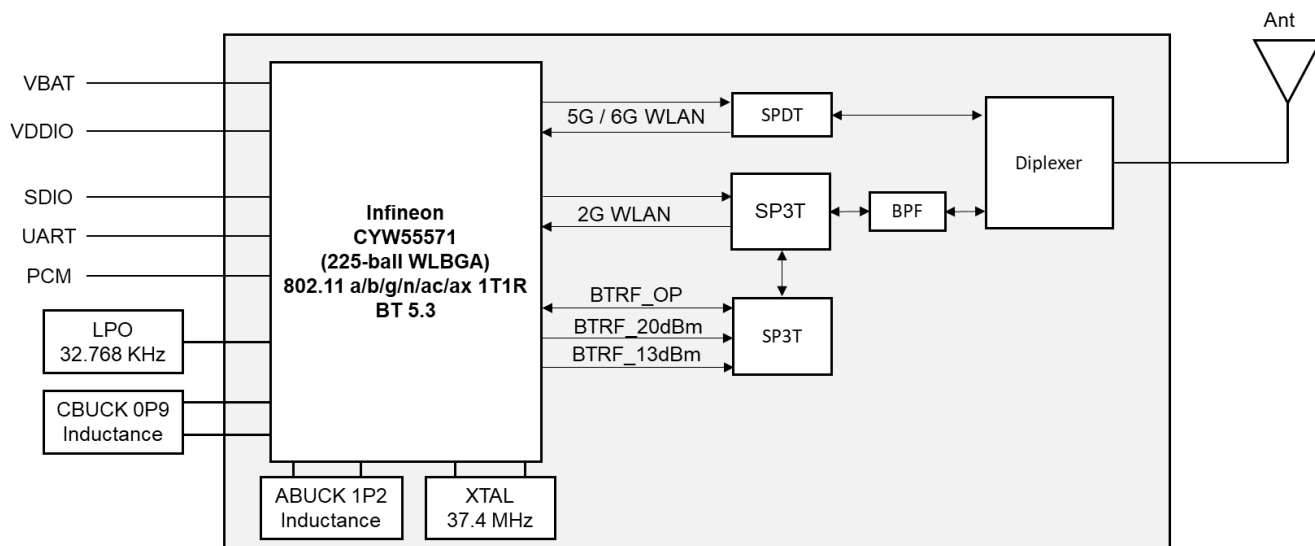
## 1. Introduction

### 1.1 Product Overview

The AW-XM632-SURX provides the highest level of integration for Commercial and Consumer IoT wireless systems with integrated tri-band 1x1 IEEE 802.11ax WLAN MAC/baseband/radio, Bluetooth 5.3 MAC/baseband/radio, and integrated Power Management Unit. WLAN and Bluetooth radios also include on-chip power amplifiers and low-noise amplifiers to further reduce the need for external components.

WLAN interfaces to host processor through a SDIO 3.0 interface while Bluetooth host interface is provided through high-speed 4-wire UART interface. Additionally, the Bluetooth section supports PCM and I2S interfaces for audio applications. AW-XM632-SURX is qualified to operate across Industrial (−40°C to +85°C) temperature range.

### 1.2 Block Diagram



**AW-XM632-SURX Block Diagram**

## 1.3 Specifications Table

### 1.3.1 General

Features	Description
<b>Product Description</b>	802.11 a/b/g/n/ac/ax Wi-Fi 6E + Bluetooth 5.3 Combo Module
<b>Major Chipset</b>	Infineon CYW55571 WLBGA
<b>Host Interface</b>	Wi-Fi + BT → SDIO + UART
<b>Dimension</b>	12 mm x 12 mm x 1.8 mm
<b>Form factor</b>	LGA, 47 pins
<b>Antenna</b>	Tri-band 1x1 ANT : Wi-Fi/Bluetooth → TX/RX
<b>Weight</b>	TBD

### 1.3.2 WLAN

Features	Description
<b>WLAN Standard</b>	IEEE 802.11 a/b/g/n/ac/ax
<b>WLAN VID/PID</b>	N/A
<b>WLAN SVID/SPID</b>	N/A
<b>Frequency Range</b>	WLAN: 2.4 / 5 / 6 GHz Band
<b>Modulation</b>	DSSS DBPSK(1Mbps), DQPSK(2Mbps), CCK(11/5.5Mbps) OFDM BPSK(9/6Mbps/MCS0), QPSK(18/12Mbps/MCS1~2), 16-QAM(36/24Mbps/MCS3~4), 64-QAM(72.2/54/48Mbps/MCS5~7), 256-QAM(MCS8~9), 1024-QAM(MCS10~11)
<b>Number of Channels</b>	<b>2.4GHz</b> <ul style="list-style-type: none"> <li>● USA, Canada and Taiwan – 1 ~ 11</li> <li>● China, Most European Countries – 1 ~ 13</li> <li>● Japan, 1 ~ 13</li> </ul> <b>5GHz</b> <ul style="list-style-type: none"> <li>● USA, EUROPE – 36, 40, 44, 48, 52, 56, 60, 64, 100, 104, 108, 112, 116, 120, 124, 128, 132, 136, 140, 149, 153, 157, 161, 165</li> </ul> <b>6GHz</b> <ul style="list-style-type: none"> <li>● CH1~CH233</li> </ul>

<b>Output Power<sup>1,2</sup></b> <b>(Board Level Limit)*</b>	<b>2.4G</b>				
		Min	Typ	Max	Unit
	11b (11Mbps) @EVM<8%	16	18	20	dBm
	11g (54Mbps) @EVM ≤ -25 dB	15	17	19	dBm
	11n (HT20 MCS7) @EVM ≤ -27 dB	14.5	16.5	18.5	dBm
	11ax (HE20 MCS11) @EVM ≤ -35 dB	12	14	16	dBm
	<b>5G</b>				
		Min	Typ	Max	Unit
	11a (54Mbps) @EVM<-25 dB	14	16	18	dBm
	11n (HT20 MCS7) @EVM ≤ -27 dB	14	16	18	dBm
	11n (HT40 MCS7) @EVM ≤ -27 dB	14	16	18	dBm
	11ac (VHT20 MCS8) @EVM ≤ -30 dB	13.5	15.5	17.5	dBm
	11ac (VHT40 MCS9) @EVM ≤ -32 dB	12.5	14.5	16.5	dBm
	11ac (VHT80 MCS9) @EVM ≤ -32 dB	12	14	16	dBm
	11ax (HE20 MCS11) @EVM ≤ -35 dB	12.5	14.5	16.5	dBm
	11ax (HE40 MCS11) @EVM ≤ -35 dB	12	14	16	dBm
	11ax (HE80 MCS11) @EVM ≤ -35 dB	11.5	13.5	15.5	dBm
	<b>6G</b>				
		Min	Typ	Max	Unit
	11ax (HE20 MCS11) @EVM ≤ -35 dB	10	12	14	dBm
	11ax (HE40 MCS11) @EVM ≤ -35 dB	9	11	13	dBm
	11ax (HE80 MCS11) @EVM ≤ -35 dB	8	10	12	dBm

<sup>1</sup> Unless otherwise stated, limit values apply for an ambient temperature of +25 °C.

<sup>2</sup> Tx power variation ±3.0 dB for process, voltage and temperature variation across -40°C to +85°C.

<b>Receiver Sensitivity**</b>	<b>2.4G</b>				
		Min	Typ	Max	Unit
	11b (11Mbps)		88	85	dBm
	11g (54Mbps)		76	73	dBm
	11n (HT20 MCS7)		74	71	dBm
	11ax (HE20 MCS11)		63	60	dBm
	<b>5G</b>				
		Min	Typ	Max	Unit
	11a (54Mbps)		74	71	dBm
	11n (HT20 MCS7)		72	69	dBm
	11n (HT40 MCS7)		69	66	dBm
	11ac (VHT20 MCS8)		67	64	dBm
	11ac (VHT40 MCS9)		63	60	dBm
	11ac (VHT80 MCS9)		60	57	dBm
	11ax (HE20 MCS11)		60	57	dBm
	11ax (HE40 MCS11)		56	53	dBm
	11ax (HE80 MCS11)		55	52	dBm
	<b>6G</b>				
		Min	Typ	Max	Unit
	11ax (HE20 MCS11)		56	53	dBm
	11ax (HE40 MCS11)		54	51	dBm
	11ax (HE80 MCS11)		52	49	dBm
<b>Data Rate</b>	802.11b: 1, 2, 5.5, 11Mbps 802.11g: 6, 9, 12, 18, 24, 36, 48, 54Mbps 802.11n: MCS0~7 HT20/HT40 802.11a: 6, 9, 12, 18, 24, 36, 48, 54Mbps 802.11ac: MCS0~8 VHT20 802.11ac: MCS0~9 VHT40/VHT80 802.11ax: MCS10~11 HE20/HE40/HE80				
<b>Security</b>	<ul style="list-style-type: none"> <li>● WEP</li> <li>● WPA/WPA2/WPA3 Enterprise with 192-bit encryption</li> <li>● WMM, WMM-PS (U-APSD), WMM-SA</li> <li>● AES (hardware accelerator),</li> <li>● TKIP (hardware accelerator)</li> <li>● CKIP (software support)</li> </ul>				

\* If you have any certification questions about output power please contact FAE directly

\*\* Project is in engineering stage, RF performance is still being verified.



### 1.3.3 Bluetooth

Features	Description				
Bluetooth Standard	Bluetooth 5.3				
Bluetooth VID/PID	N/A				
Frequency Range	2400~2483.5MHz				
Modulation	GFSK (1Mbps), $\pi/4$ DQPSK (2Mbps) and 8DPSK (3Mbps)				
Output Power*		Min	Typ	Max	Unit
	BDR	3	6	9	dBm
	Low Energy (2MHz)	3	6	9	dBm
Receiver Sensitivity**		Min	Typ	Max	Unit
	BDR		-90	-87	dBm
	EDR		-86	-83	dBm
	Low Energy (2MHz)		-92	-89	dBm

\* If you have any certification questions about output power please contact FAE directly

\*\* Project is in engineering stage, RF performance is still being verified.

### 1.3.4 Operating Conditions

Features	Description
<b>Operating Conditions</b>	
Voltage	3.3V
Operating Temperature	-40°C to 85°C
Operating Humidity	less than 85% R.H.
Storage Temperature	-40°C to 125°C
Storage Humidity	less than 60% R.H.
<b>ESD Protection</b>	
Human Body Model	TBD
Changed Device Model	TBD

## 1.4 Frequency references

### 1.4.1 External 32.768 kHz sleep clock specifications

AW-XM632-SURX requires an external low-frequency clock for low-power mode timing. An external 32.768 kHz precision oscillator which meets the requirements listed must be used.

#### External 32.768 kHz sleep clock specifications

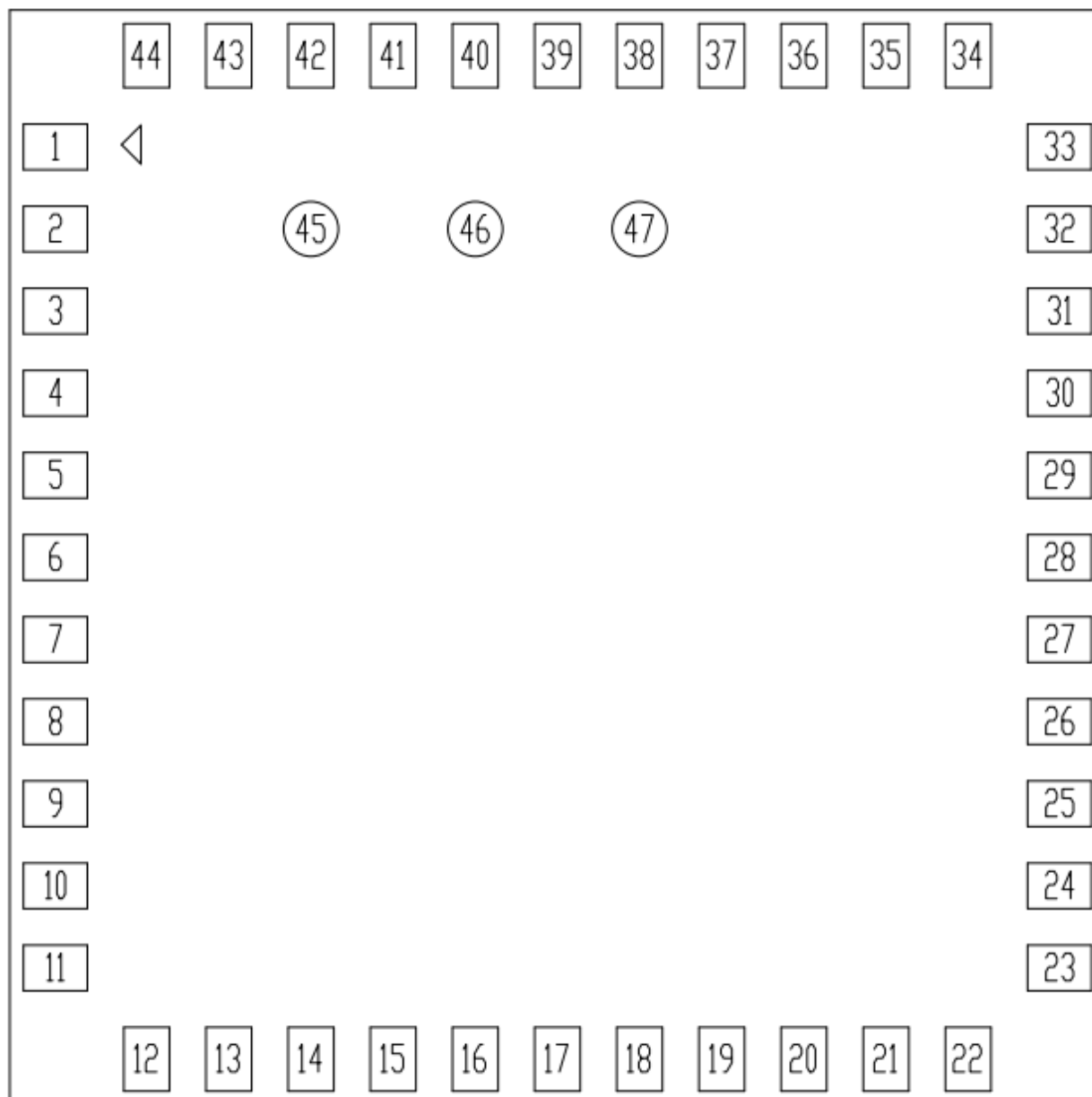
Parameter	LPO clock	Unit
Nominal input frequency	32.768	kHz
Frequency accuracy	±250	ppm
Duty cycle	30 – 70	%
Input signal amplitude	200–1800	mV, p–p
Signal type	Square-wave or sine-wave	-
Input impedance <sup>1</sup>	> 100k	Ω
Clock jitter <sup>2</sup> (during initial startup)	< 5	pF
	< 10,000	ppm

#### Notes:

1. When power is applied or switched off.
2. The LPO\_IN input receiver has ac-coupled capacitance on the input with the feedback resistor to maintain the common mode around VDDIO/2 and power supply noise should be maintained less than 100mV to avoid any false glitches before the time constant (ac- coupled capacitance \* feedback resistor, i.e., 100 μs) settles down.

## 2. Pin Definition

### 2.1 Pin Map



**AW-XM632-SURX Pin Map (Top View)**

## 2.2 Pin Table

Pin No	Definition	Basic Description	Voltage	Type
1	GND	Ground.	-	GND
2	ANT	WLAN/BT RF ANT.		RF
3	GND	Ground.	-	GND
4	NC	Floating	-	-
5	GND	Ground.	-	GND
6	BT_DEV_WAKE	Bluetooth DEVICE WAKE.	VDDIO	I/O
7	BT_HOST_WAKE	Bluetooth HOST WAKE.	-	I/O
8	NC	Floating	-	-
9	VBAT	3.3V power pin.	3.3V	PWR
10	NC		-	-
11	NC		-	-
12	WL_REG_ON	Used by the PMU to power up or power down the internal AW-XM632-SURX regulators used by the WLAN section. When deasserted, this pin holds the WLAN section in reset. This pin has an internal 50 K $\Omega$ pull-down resistor that is auto enabled/disabled by programming.	VDDIO	I
13	WL_HOST_WAKE	WLAN HOST_WAKE.	VDDIO	I/O
14	SDIO_DATA_2	SDIO data line 2	-	I/O
15	SDIO_DATA_3	SDIO data line 3	-	I/O
16	SDIO_DATA_CMD	SDIO command line	-	I/O
17	SDIO_DATA_CLK	SDIO Clock Input	-	I
18	SDIO_DATA_0	SDIO data line 0	-	I/O
19	SDIO_DATA_1	SDIO data line 1	-	I/O
20	GND	Ground.	-	GND
21	CSR_VLX	CSR Power Stage Output to Inductor.	0.9V	O
22	VDDIO	1.8 V IO Supply for WLAN GPIOs.	1.8V	PWR
23	CBUCK_0P9	Internal Buck 0.9V voltage generation pin.	0.9V	I

24	LPO_IN	External Sleep Clock Input (32.768 kHz)	-	I
25	BT_PCM_OUT	PCM data output.	VDDIO	O
26	BT_PCM_CLK	PCM clock	VDDIO	I/O
27	BT_PCM_IN	PCM data input.	VDDIO	I
28	BT_PCM_SYNC	PCM sync signal	VDDIO	I/O
29	NC	Floating	-	-
30	NC	Floating	-	-
31	GND	Ground.	-	GND
32	NC	Floating	-	-
33	GND	Ground.	-	GND
34	BT_REG_ON	Used by the PMU to power up or power down the internal regulators used by the Bluetooth® section. When deasserted, this pin holds the Bluetooth section in reset. This pin has an internal 50 kΩ pull-down resistor that is auto enabled/disabled by programming.	VDDIO	I
35	GPIO_2	WLAN General Purpose I/O	VDDIO	I/O
36	GND	Ground.	-	GND
37	WL_DEV_WAKE	WL_DEV_WAKE	VDDIO	I/O
38	GPIO_3	WLAN General Purpose I/O	VDDIO	I/O
39	GPIO_4	WLAN General Purpose I/O	VDDIO	I/O
40	GPIO_5	WLAN General Purpose I/O	VDDIO	I/O
41	BT_UART_RTS_N	UART request-to-send. Active-low request-to-send signal for the HCI UART interface. BT LED control pin.	VDDIO	O
42	BT_UART_TXD	UART Serial Output. Serial data output for the HCI UART interface.	VDDIO	O
43	BT_UART_RXD	UART serial input. Serial data input for the HCI UART interface.	VDDIO	I
44	BT_UART_CTS_N	UART clear-to-send. Active-low clear-to-send signal for the HCI UART interface.	VDDIO	I
45	BT_GPIO_2	Bluetooth General Purpose I/O	VDDIO	I/O
46	NC	Floating	-	-
47	NC	Floating	-	-

### 3. Electrical Characteristics

#### 3.1 Absolute Maximum Ratings

Symbol	Parameter	Minimum	Typical	Maximum	Unit
<b>VBAT</b>	DC supply for the VBAT and PA driver supply	-0.5	-	6.0	V
<b>VDDIO</b>	DC supply voltage for digital I/O	-0.5	-	2.2	V
<b>T<sub>j</sub></b>	Maximum junction temperature	-	-	125	°C

#### 3.2 Recommended Operating Conditions

Symbol	Parameter	Minimum	Typical	Maximum	Unit
<b>VBAT</b>	Power supply for Internal Regulator	3.13	3.3	3.47	V
<b>VDDIO</b>	DC supply voltage for digital I/O	1.71	1.8	1.89	V

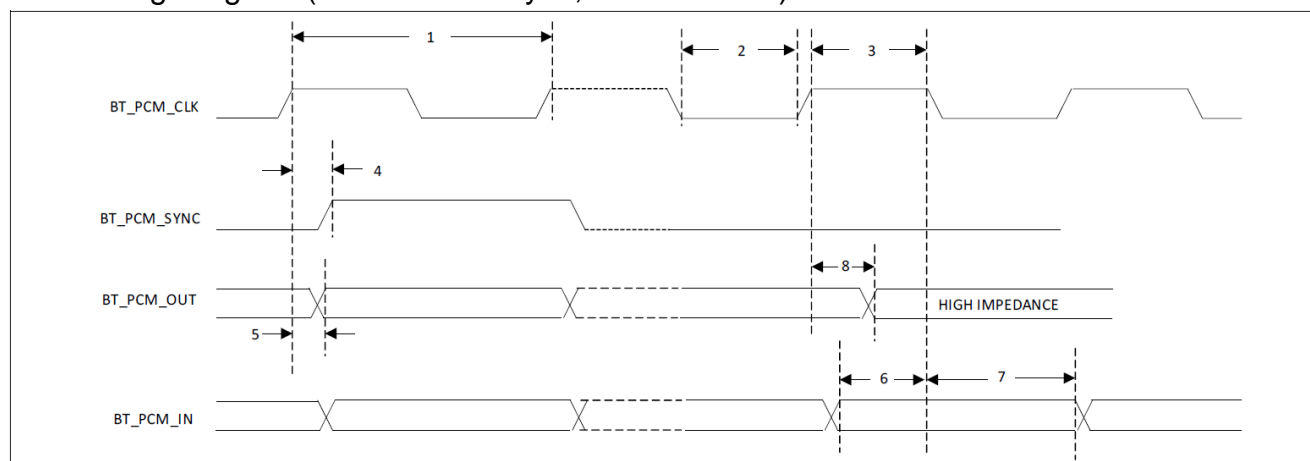
#### 3.3 Digital IO Pin DC Characteristics

Symbol	Parameter	Minimum	Typical	Maximum	Unit
<b>Digital I/O pins, VDDIO=1.8V</b>					
<b>V<sub>IH</sub></b>	Input high voltage	0.65 × VDDIO	-	-	V
<b>V<sub>IL</sub></b>	Input low voltage	-	-	0.35 × VDDIO	V
<b>V<sub>OH</sub></b>	Output high voltage	VDDIO – 0.40	-	-	V
<b>V<sub>OL</sub></b>	Output Low Voltage	-	-	0.45	V
<b>WL_REG_ON &amp; BT_REG_ON Pins</b>					
-	Input high voltage	1.2	-	VBAT	-
-	Input low voltage	-	-	0.3	-

## 3.4 Host Interface

### 3.4.1 PCM Interface Timing

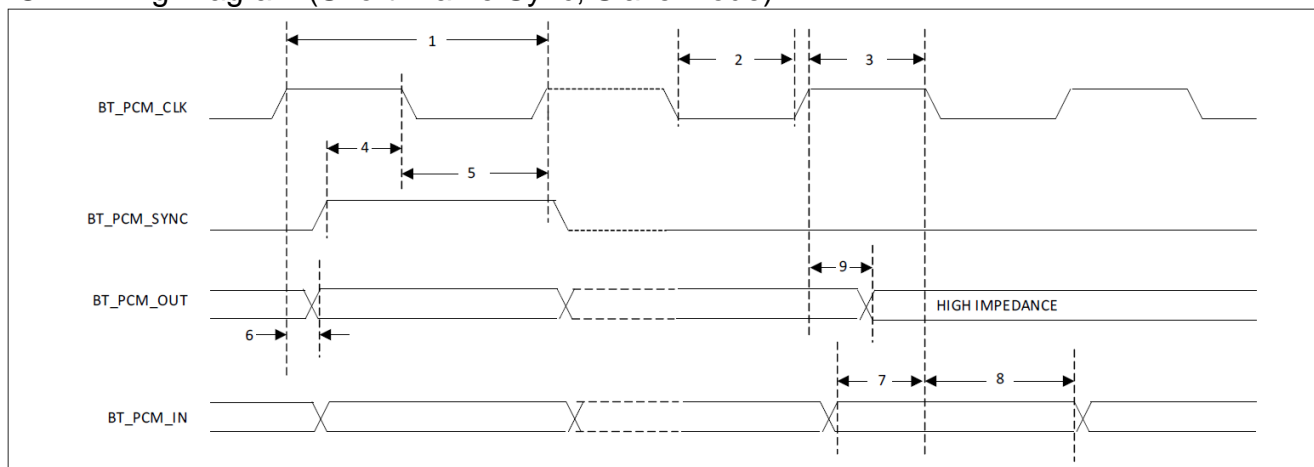
#### ■ PCM Timing Diagram (Short Frame Sync, Master Mode)



#### PCM Interface Timing Specifications (Short Frame Sync, Master Mode)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	12	MHz
2	PCM bit clock LOW	41	—	—	ns
3	PCM bit clock HIGH	41	—	—	ns
4	PCM_SYNC delay	0	—	25	ns
5	PCM_OUT delay	0	—	25	ns
6	PCM_IN setup	8	—	—	ns
7	PCM_IN hold	8	—	—	ns
8	Delay from rising edge of PCM_BCLK during last bit period to PCM_OUT becoming high impedance	0	—	25	ns

## ■ PCM Timing Diagram (Short Frame Sync, Slave Mode)

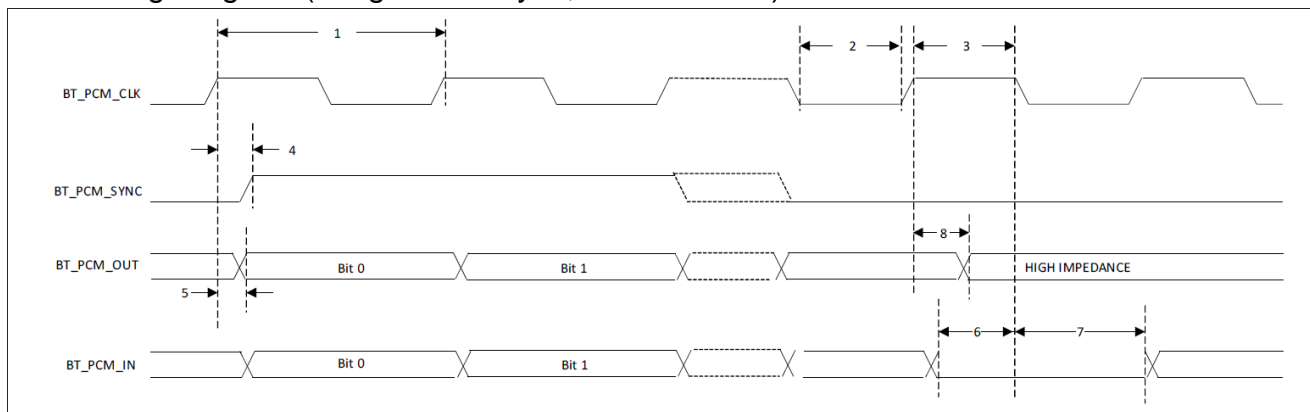


## PCM Interface Timing Specifications (Short Frame Sync, Slave Mode)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	12	MHz
2	PCM bit clock LOW	41	—	—	ns
3	PCM bit clock HIGH	41	—	—	ns
4	PCM_SYNC setup	8	—	—	ns
5	PCM_SYNC hold	8	—	—	ns
6	PCM_OUT delay	0	—	25	ns
7	PCM_IN setup	8	—	—	ns
8	PCM_IN hold	8	—	—	ns
9	Delay from rising edge of PCM_BCLK during last bit period to PCM_OUT becoming high impedance	0		25	ns



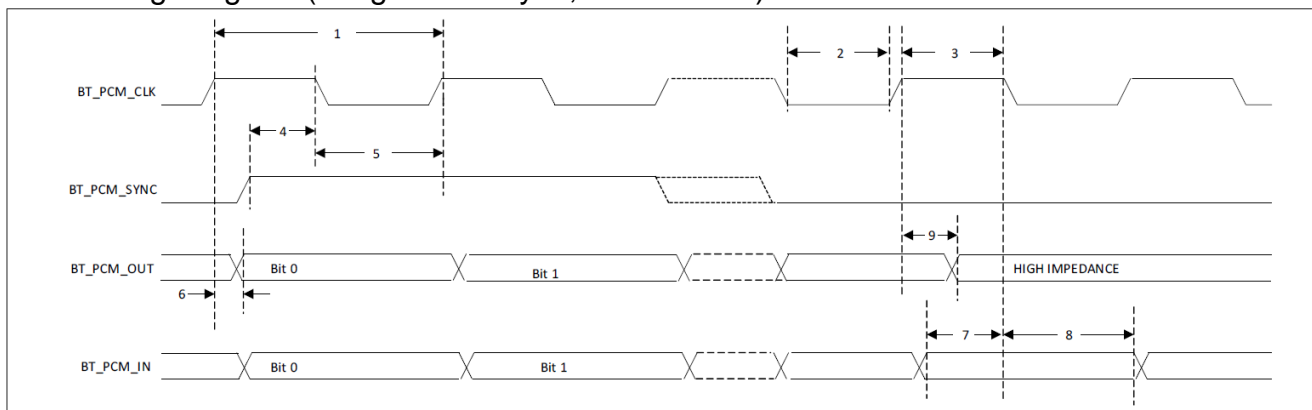
## ■ PCM Timing Diagram (Long Frame Sync, Master Mode)



## PCM Interface Timing Specifications (Long Frame Sync, Master Mode)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	12	MHz
2	PCM bit clock LOW	41	—	—	ns
3	PCM bit clock HIGH	41	—	—	ns
4	PCM_SYNC delay	0	—	25	ns
5	PCM_OUT delay	0	—	25	ns
6	PCM_IN setup	8	—	—	ns
7	PCM_IN hold	8	—	—	ns
8	Delay from rising edge of PCM_BCLK during last bit period to PCM_OUT becoming high impedance	0	—	25	ns

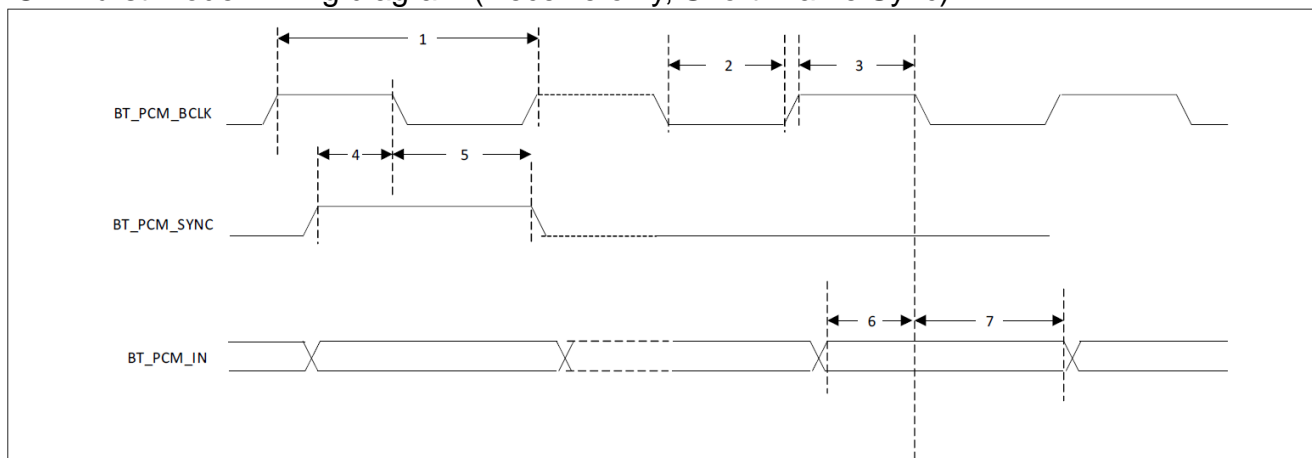
## ■ PCM Timing Diagram (Long Frame Sync, Slave Mode)



## PCM Interface Timing Specifications (Long Frame Sync, Slave Mode)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	12	MHz
2	PCM bit clock LOW	41	—	—	ns
3	PCM bit clock HIGH	41	—	—	ns
4	PCM_SYNC setup	8	—	—	ns
5	PCM_SYNC hold	8	—	—	ns
6	PCM_OUT delay	0	—	25	ns
7	PCM_IN setup	8	—	—	ns
8	PCM_IN hold	8	—	—	ns
9	Delay from rising edge of PCM_BCLK during last bit period to PCM_OUT becoming high impedance	0	—	25	ns

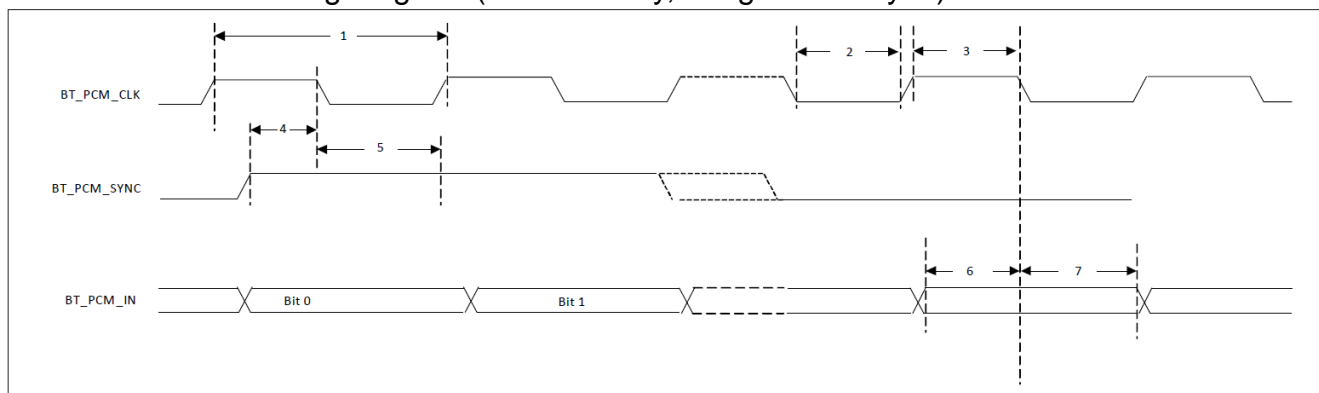
■ PCM Burst Mode Timing diagram (Receive only, Short Frame Sync)



PCM Burst Mode (Receive Only, Short Frame Sync)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	24	MHz
2	PCM bit clock LOW	20.8	—	—	ns
3	PCM bit clock HIGH	20.8	—	—	ns
4	PCM_SYNC setup	8	—	—	ns
5	PCM_SYNC hold	8	—	—	ns
6	PCM_IN setup	8	—	—	ns
7	PCM_IN hold	8	—	—	ns

■ PCM Burst Mode Timing diagram (Receive only, Long Frame Sync)



PCM Burst Mode (Receive Only, Long Frame Sync)

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	PCM bit clock frequency	—	—	24	MHz
2	PCM bit clock LOW	20.8	—	—	ns
3	PCM bit clock HIGH	20.8	—	—	ns
4	PCM_SYNC setup	8	—	—	ns
5	PCM_SYNC hold	8	—	—	ns
6	PCM_IN setup	8	—	—	ns
7	PCM_IN hold	8	—	—	ns

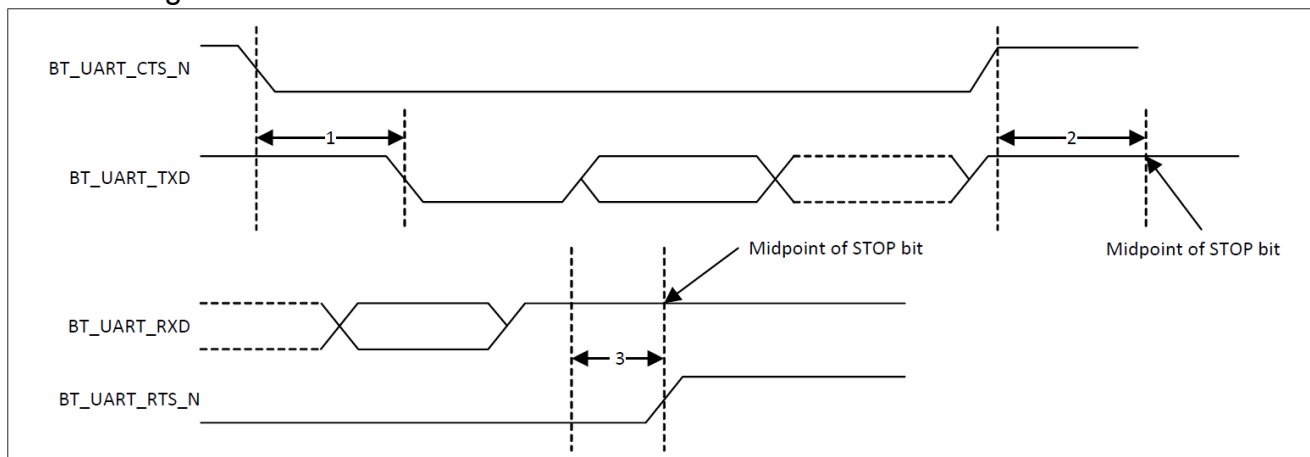
### 3.4.2 UART Interface

The AW-XM632-SURX UART is a standard 4-wire interface (RX, TX, RTS, and CTS) with adjustable baud rates from 9600 bps to 4.0 Mbps. The baud rate may be selected through a vendor-specific UART HCI command. UART has a 1040-byte receive FIFO and a 1040-byte transmit FIFO to support EDR. Access to the FIFOs is conducted through the AHB interface through either DMA/CPU. The UART supports the Bluetooth 5.0 UART HCI specification. The default baud rate is 115.2 Kbaud.

The AW-XM632-SURX UART can perform XON/XOFF flow control and includes hardware support for the Serial Line Input Protocol (SLIP). It can also perform wake-on activity. For example, activity on the RX or CTS inputs can wake the chip from a sleep state.

Normally, the UART baud rate is set by a configuration record downloaded after device reset and the host does not need to adjust the baud rate. Support for changing the baud rate during normal HCI UART operation is included through a vendor-specific command that allows the host to adjust the contents of the baud rate registers. The AW-XM632-SURX UARTs operate correctly with the host UART as long as the combined baud rate error of the two devices is within  $\pm 2\%$ .

#### ■ UART Timing

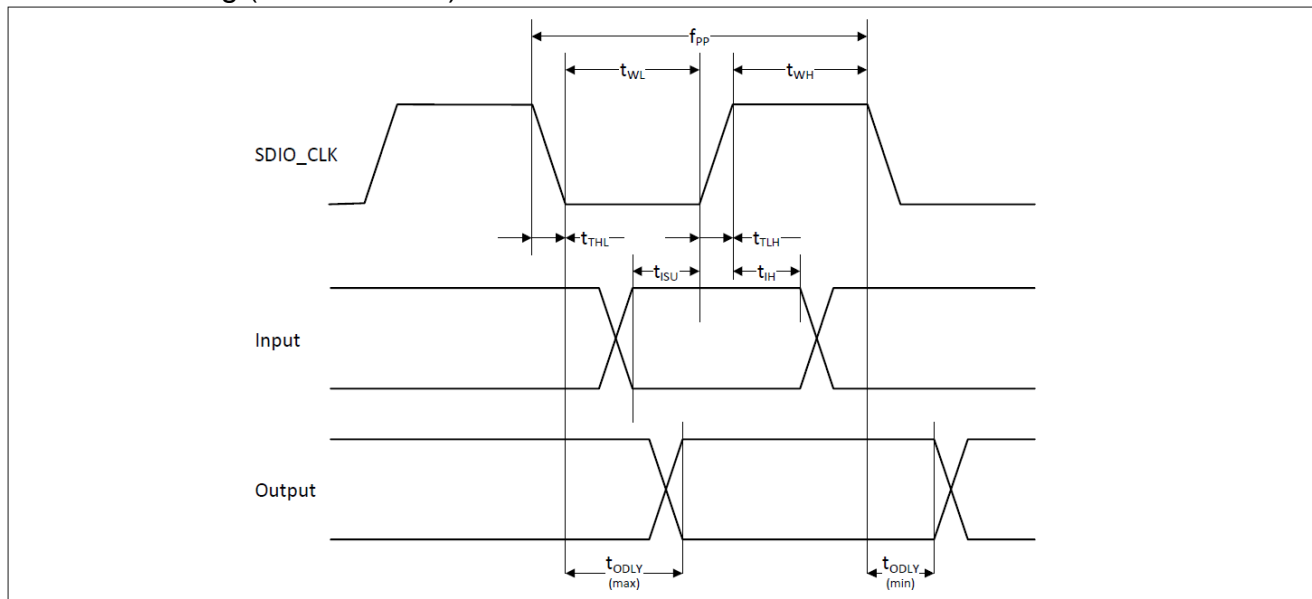


#### UART Timing specifications

Reference	Characteristics	Minimum	Typical	Maximum	Unit
1	Delay time, BT_UART_CTS_N low to BT_UART_TXD valid	—	—	1.5	Bit periods
2	Setup time, BT_UART_CTS_N high before midpoint of stop bit	—	—	0.5	Bit periods
3	Delay time, midpoint of stop bit to BT_UART_RTS_N high	—	—	0.5	Bit periods

### 3.4.3 SDIO Interface

#### ■ SDIO Bus Timing (Default Mode)



SDIO Bus Timing<sup>[1]</sup> Parameters (Default Mode)

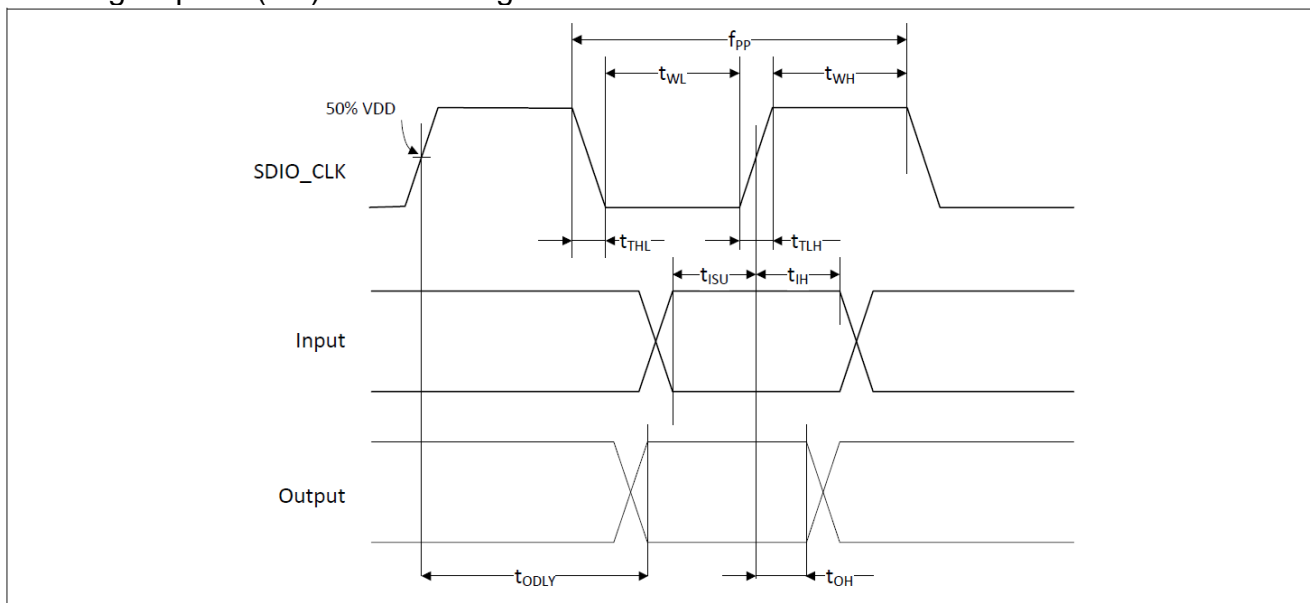
Parameter	Symbol	Minimum	Typical	Maximum	Unit
<b>SDIO CLK (All values are referred to minimum VIH and maximum VIL<sup>[2]</sup>)</b>					
Frequency – Data Transfer mode	$f_{PP}$	0	–	25	MHz
Frequency – Identification mode	$f_{OD}$	0	–	400	kHz
Clock low time	$t_{WL}$	10	–	–	ns
Clock high time	$t_{WH}$	10	–	–	ns
Clock rise time	$t_{TLH}$	–	–	10	ns
Clock low time	$t_{THL}$	–	–	10	ns
<b>Inputs: CMD, DAT (referenced to CLK)</b>					
Input setup time	$t_{ISU}$	5	–	–	ns
Input hold time	$t_{IH}$	5	–	–	ns
<b>Outputs: CMD, DAT (referenced to CLK)</b>					
Output delay time – Data Transfer mode	$t_{ODLY}$	0	–	14	ns

<b>Output delay time – Identification mode</b>	$t_{ODLY}$	0	–	50	ns
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Notes:

1. Timing is based on  $CL \leq 40$  pF load on CMD and Data..
2. Min ( $V_{ih}$ ) =  $0.7 \times V_{DDIO}$  and max ( $V_{il}$ ) =  $0.2 \times V_{DDIO}$ .

#### ■ SDIO High-Speed (HS) Mode Timing



#### SDIO Bus Timing<sup>[1]</sup> parameters (HS Mode)

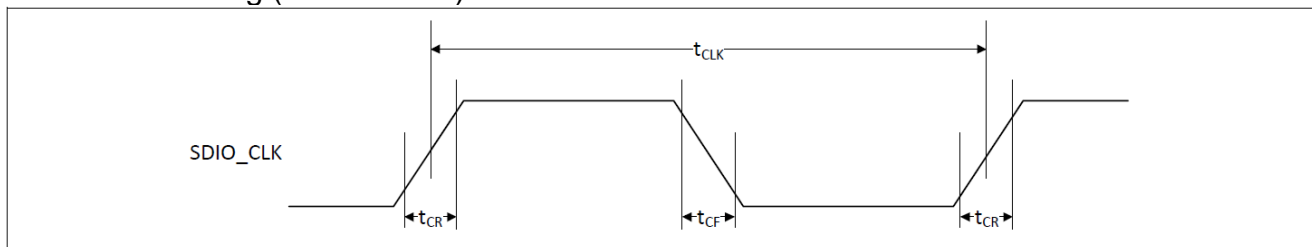
Parameter	Symbol	Minimum	Typical	Maximum	Unit
<b>SDIO CLK (all values are referred to minimum <math>V_{IH}</math> and maximum <math>V_{IL}</math><sup>[2]</sup>)</b>					
<b>Frequency – Data Transfer Mode</b>	$f_{PP}$	0	–	50	MHz
<b>Frequency – Identification Mode</b>	$f_{OD}$	0	–	400	kHz
<b>Clock low time</b>	$t_{WL}$	7	–	–	ns
<b>Clock high time</b>	$t_{WH}$	7	–	–	ns
<b>Clock rise time</b>	$t_{TLH}$	–	–	3	ns
<b>Clock low time</b>	$t_{THL}$	–	–	3	ns
<b>Inputs: CMD, DAT (referenced to CLK)</b>					
<b>Input setup Time</b>	$t_{ISU}$	6	–	–	ns
<b>Input hold Time</b>	$t_{IH}$	2	–	–	ns

Outputs: CMD, DAT (referenced to CLK)					
Output delay time – Data Transfer Mode	t <sub>ODLY</sub>	–	–	14	ns
Output hold time	t <sub>OH</sub>	2.5	–	–	ns
Total system capacitance (each line)	CL	–	–	40	pF

Notes:

1. Timing is based on CL f ≤ 40 pF load on CMD and Data.
2. Min (V<sub>ih</sub>) = 0.7 × VDDIO and max (V<sub>il</sub>) = 0.2 × VDDIO.

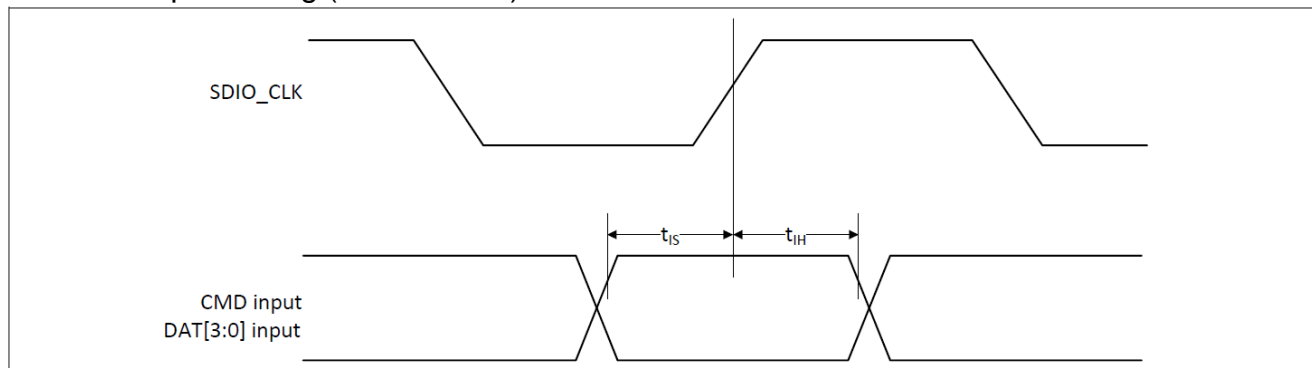
#### ■ SDIO Clock Timing (SDR Modes)



#### SDIO Bus Clock Timing parameters (SDR Modes)

Parameter	Symbol	Minimum	Typical	Unit	Comments
–	t <sub>CLK</sub>	40.0	–	ns	SDR12 mode
		20.0	–	ns	SDR25 mode
		10.0	–	ns	SDR50 mode
		4.8	–	ns	SDR104 mode
–	t <sub>CR</sub> , t <sub>CF</sub>	–	0.2 × t <sub>CLK</sub>	ns	t <sub>CR</sub> , t <sub>CF</sub> < 2.00 ns (max) @100 MHz, CCARD = 10 pF t <sub>CR</sub> , t <sub>CF</sub> < 0.96 ns (max) @208 MHz, CCARD = 10 pF
Clock duty	–	30.0	70.0	%	–

#### ■ SDIO Bus Input Timing (SDR Modes)

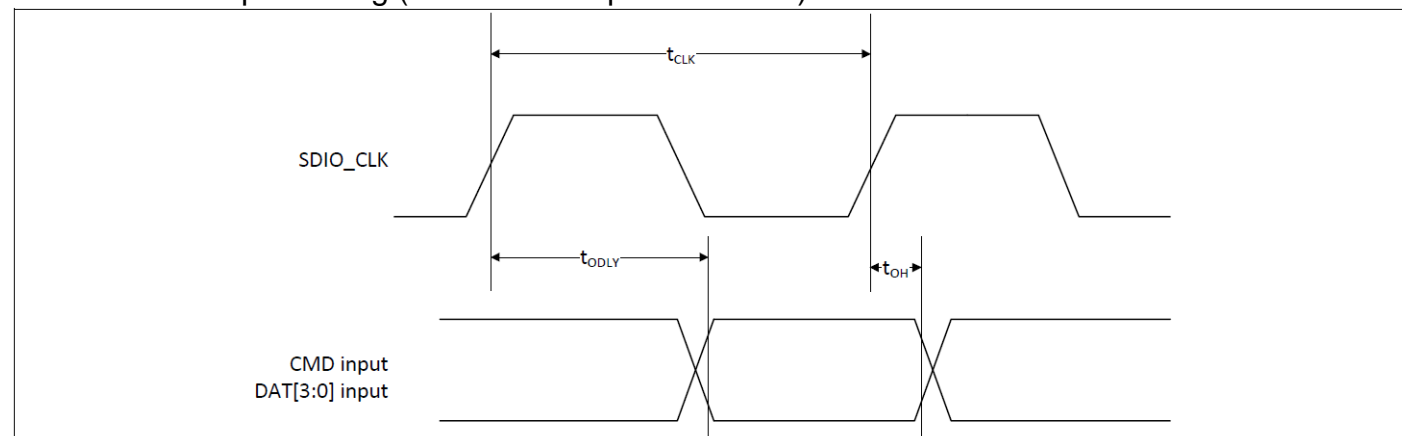




### SDIO Bus Input Timing parameters (SDR Modes)

Symbol	Minimum	Maximum	Unit	Comments
<b>SDR104 Mode</b>				
$t_{is}$	1.4	—	ns	$C_{CARD} = 10 \text{ pF}$ , $V_{CT} = 0.975 \text{ V}$
$t_{IH}$	0.80	—	ns	$C_{CARD} = 5 \text{ pF}$ , $V_{CT} = 0.975 \text{ V}$
<b>SDR50 Mode</b>				
$t_{is}$	3.00	—	ns	$C_{CARD} = 10 \text{ pF}$ , $V_{CT} = 0.975 \text{ V}$
$t_{IH}$	0.80	—	ns	$C_{CARD} = 5 \text{ pF}$ , $V_{CT} = 0.975 \text{ V}$

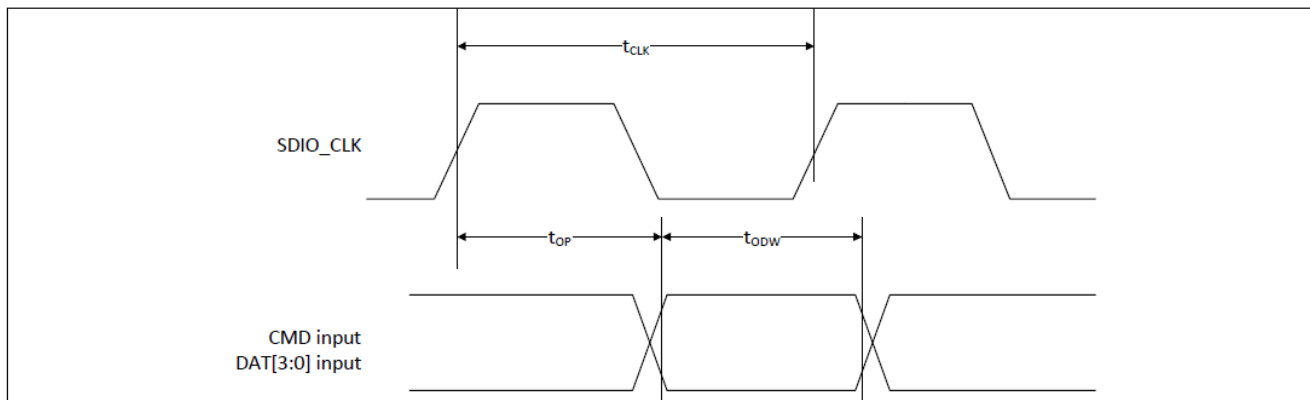
### ■ SDIO Bus Output Timing (SDR Modes up to 100 MHz)



### SDIO Bus Output Timing parameters (SDR Modes up to 100 MHz)

Symbol	Minimum	Maximum	Unit	Comments
$t_{ODLY}$	—	7.5	ns	$t_{CLK} \geq 10 \text{ ns}$ $CL = 30 \text{ pF}$ using driver type B for SDR50
$t_{ODLY}$	—	14.0	ns	$t_{CLK} \geq 20 \text{ ns}$ $CL = 40 \text{ pF}$ using for SDR12, SDR25
$t_{OH}$	1.5	—	ns	Hold time at the $t_{ODLY}$ (min) $CL = 15 \text{ pF}$

### ■ SDIO Bus Output Timing (SDR Modes 100 MHz to 208 MHz)



SDIO Bus Output Timing parameters (SDR Modes 100 MHz to 208 MHz)

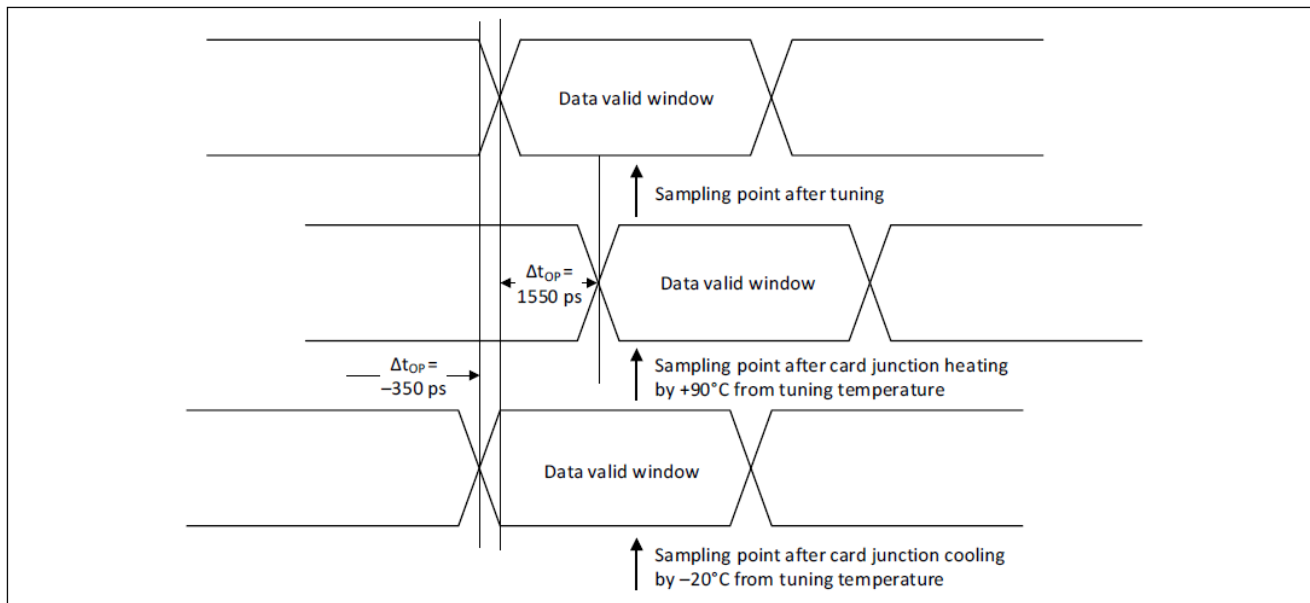
Symbol	Minimum	Maximum	Unit	Comments
$t_{OP}$	0	2.0	UI	Card output phase
$\Delta t_{OP}$	-350	+1550	ps	Delay variation due to temp change after tuning
$t_{ODW}$	0.60	—	UI	$t_{ODW}=2.88$ ns @208 MHz

$\Delta t_{OP} = +1550$  ps for junction temperature of  $\Delta t_{OP} = 90$  degrees during operation

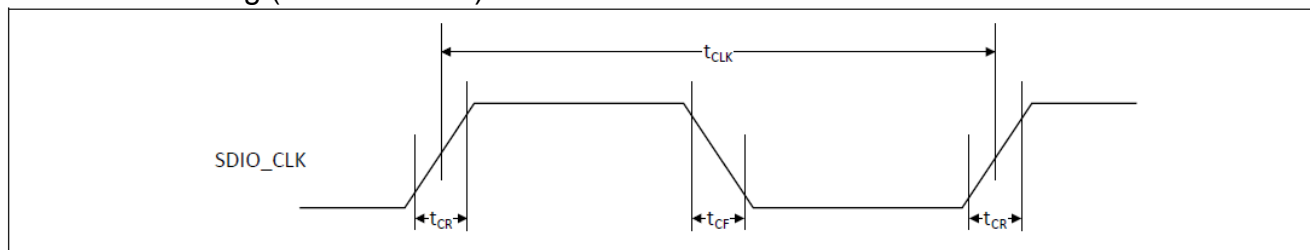
$\Delta t_{OP} = -350$  ps for junction temperature of  $\Delta t_{OP} = -20$  degrees during operation

$\Delta t_{OP} = +2600$  ps for junction temperature of  $\Delta t_{OP} = -20$  to  $+125$  degrees during operation

### ■ $\Delta t_{OP}$ Consideration for Variable Data Window (SDR 104 Mode)



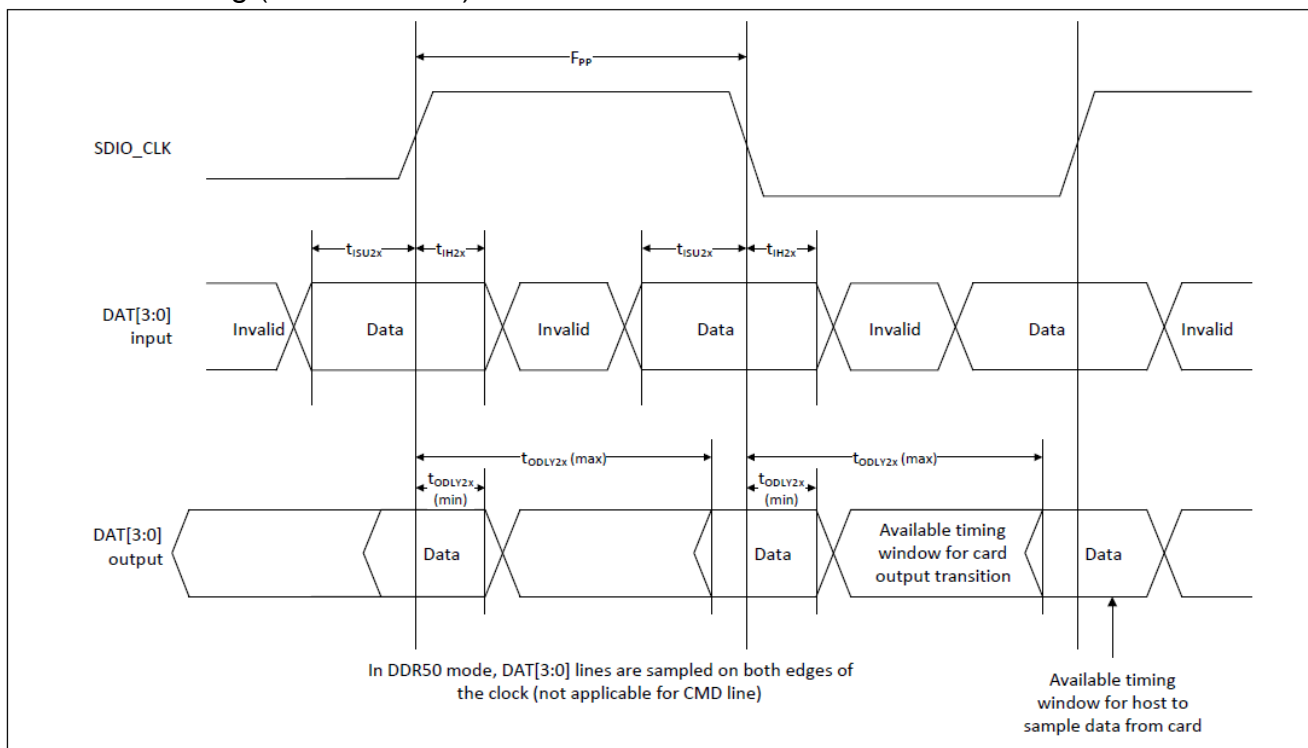
### ■ SDIO Clock Timing (DDR50 Mode)



### SDIO Bus Clock Timing parameters (DDR50 Mode)

Parameter	Symbol	Minimum	Maximum	Unit	Comments
—	$t_{CLK}$	20.0	—	ns	DDR50 mode
—	$t_{CR}, t_{CF}$	—	$0.2 \times t_{CLK}$	ns	$t_{CR}, t_{CF} < 4.00$ ns (max) @50 MHz, $C_{CARD} = 10$ pF
<b>Clock duty</b>	—	45.0	55.0	%	—

## ■ SDIO Data Timing (DDR50 Mode)



## SDIO Bus Timing parameters (DDR50 Mode)

Parameter	Symbol	Minimum	Maximum	Unit	Comments
<b>Input CMD</b>					
Input setup time	$t_{ISU}$	6.0	—	ns	CCARD < 10pF (1 Card)
Input hold time	$t_{IH}$	0.8	—	ns	CCARD < 10pF (1 Card)
<b>Output CMD</b>					
Output delay time	$t_{ODLY}$	—		ns	CCARD < 30pF (1 Card)
Output hold time	$t_{OH}$	1.5	—	ns	CCARD < 15pF (1 Card)
<b>Input DAT</b>					
Input setup time	$t_{ISU2x}$	3.0	—	ns	CCARD < 10pF (1 Card)
Input hold time	$t_{IH2x}$	0.8	—	ns	CCARD < 10pF (1 Card)
<b>Output DAT</b>					
Output delay time	$t_{ODLY2x}$	—	7.5	ns	CCARD < 25pF (1 Card)
Output hold time	$t_{ODLY2x}$	1.5	—	ns	CCARD < 15pF (1 Card)

## 3.5 Power up Timing Sequence

AW-XM632-SURX has two signals that allow the host to control power consumption by enabling or disabling the Bluetooth, WLAN, and internal regulator blocks. These signals are described below. Additionally, diagrams are provided to indicate proper sequencing of the signals for various operational states. The timing values indicated are minimum required values; longer delays are also acceptable.

### 3.5.1 Description of Control Signals

■ **WL\_REG\_ON**: Used by the PMU to power up the WLAN section. It is also OR-gated with the BT\_REG\_ON input to control the internal AW-XM632-SURX regulators. When this pin is high, the regulators are enabled and the WLAN section is out of reset. When this pin is low the WLAN section is in reset. If both the BT\_REG\_ON and WL\_REG\_ON pins are low, the regulators are disabled.

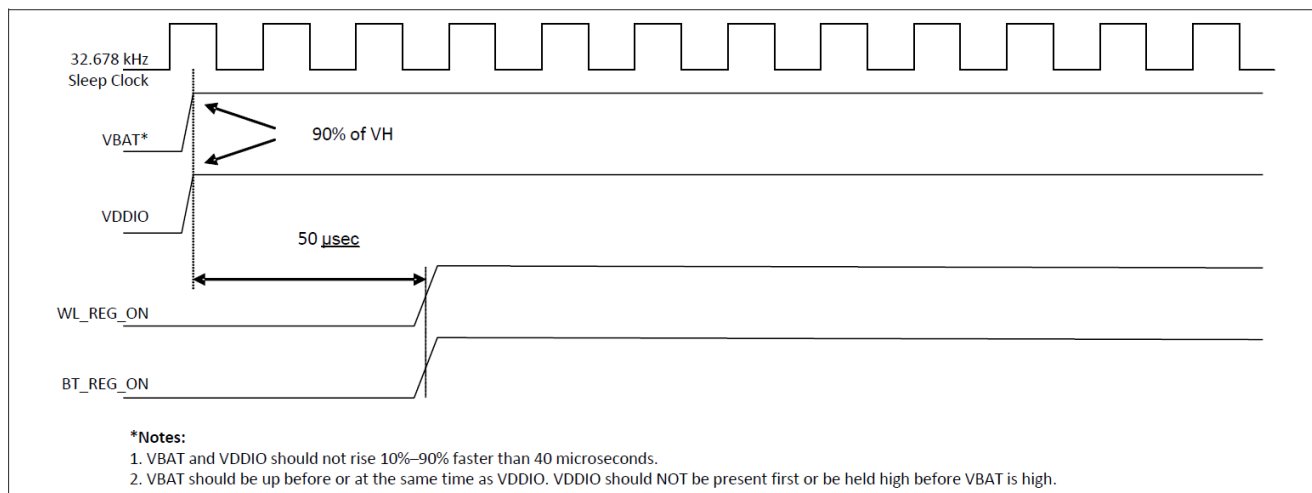
■ **BT\_REG\_ON**: Used by the PMU (OR-gated with WL\_REG\_ON) to power up the internal AW-XM632-SURX regulators. If both the BT\_REG\_ON and WL\_REG\_ON pins are low, the regulators are disabled. When this pin is low and WL\_REG\_ON is high, the Bluetooth section is in reset.

■ **Note**

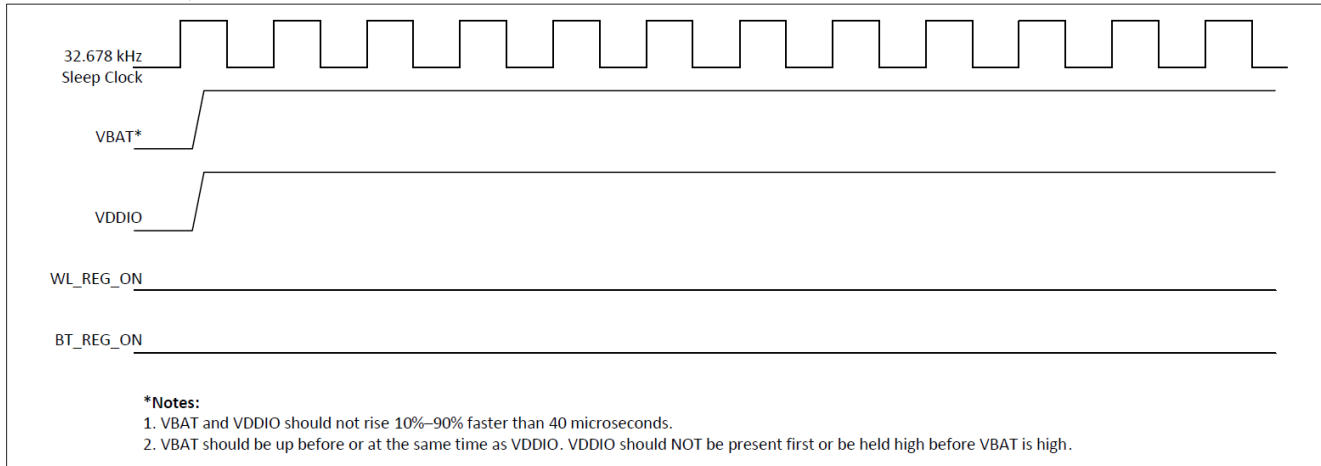
VBAT and VDDIO should not rise 10%–90% faster than 40 microseconds.

### 3.5.2 Control Signal Timing Diagrams

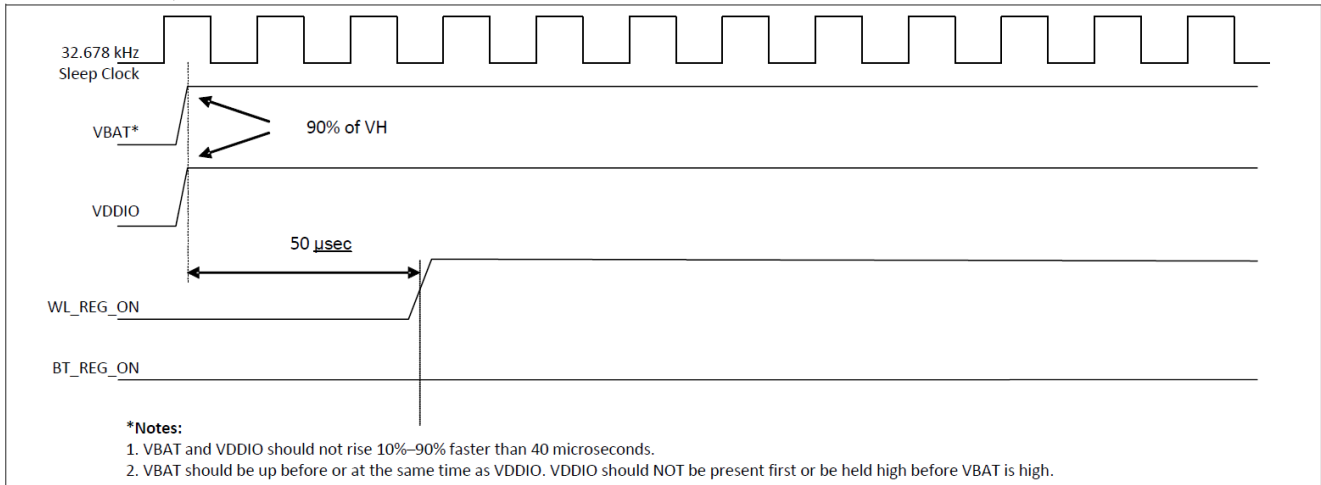
■ **WLAN = ON, Bluetooth = ON**



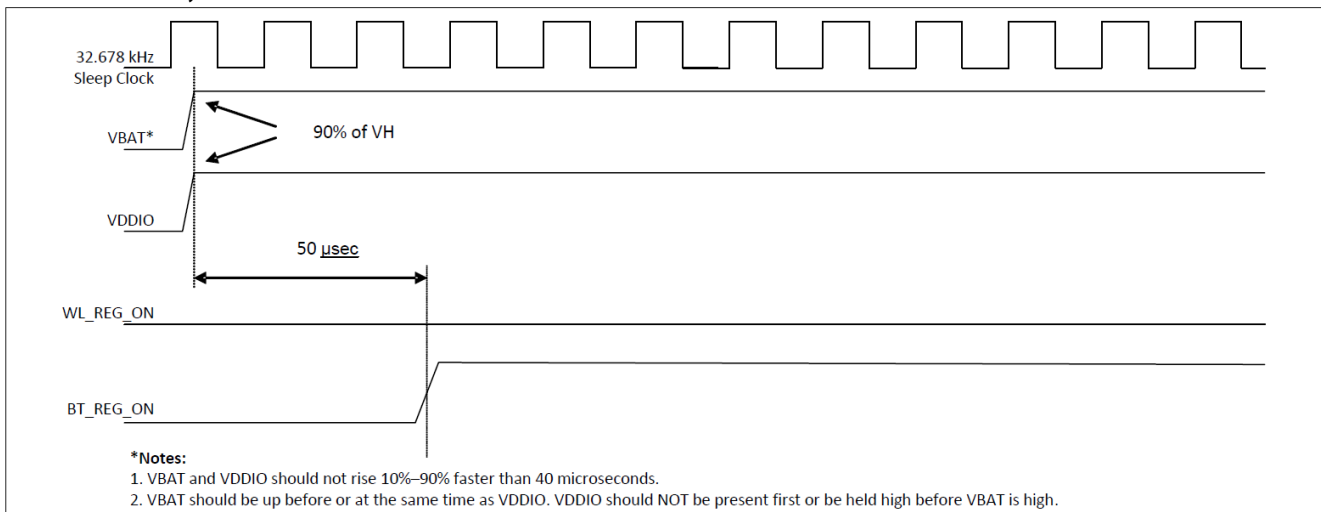
### ■ WLAN = OFF, Bluetooth = OFF



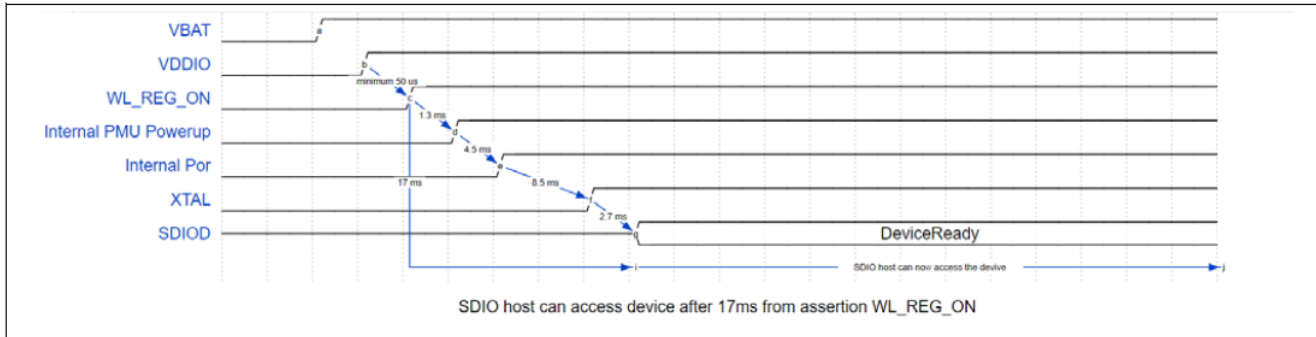
### ■ WLAN = ON, Bluetooth = OFF



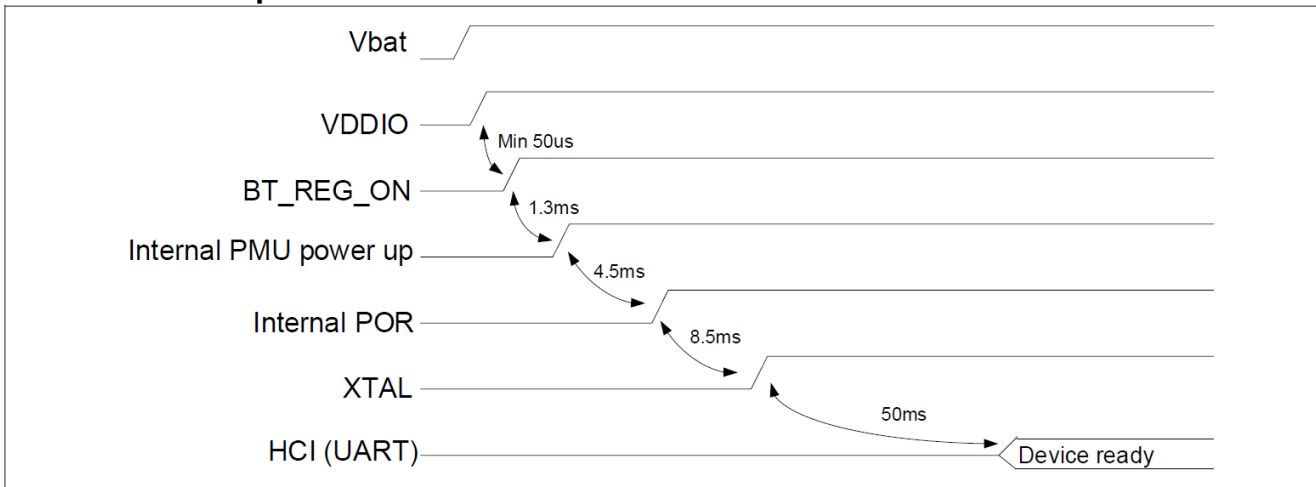
### ■ WLAN = OFF, Bluetooth = ON



## ■ WLAN Boot-Up Sequence for SDIO Host



## ■ Bluetooth Boot-Up for HCI



### **3.6 Power Consumption\***

#### **3.6.1 WLAN**

TBD

\* The power consumption is based on Azurewave test environment, these data for reference only.

#### **3.6.2 Bluetooth**

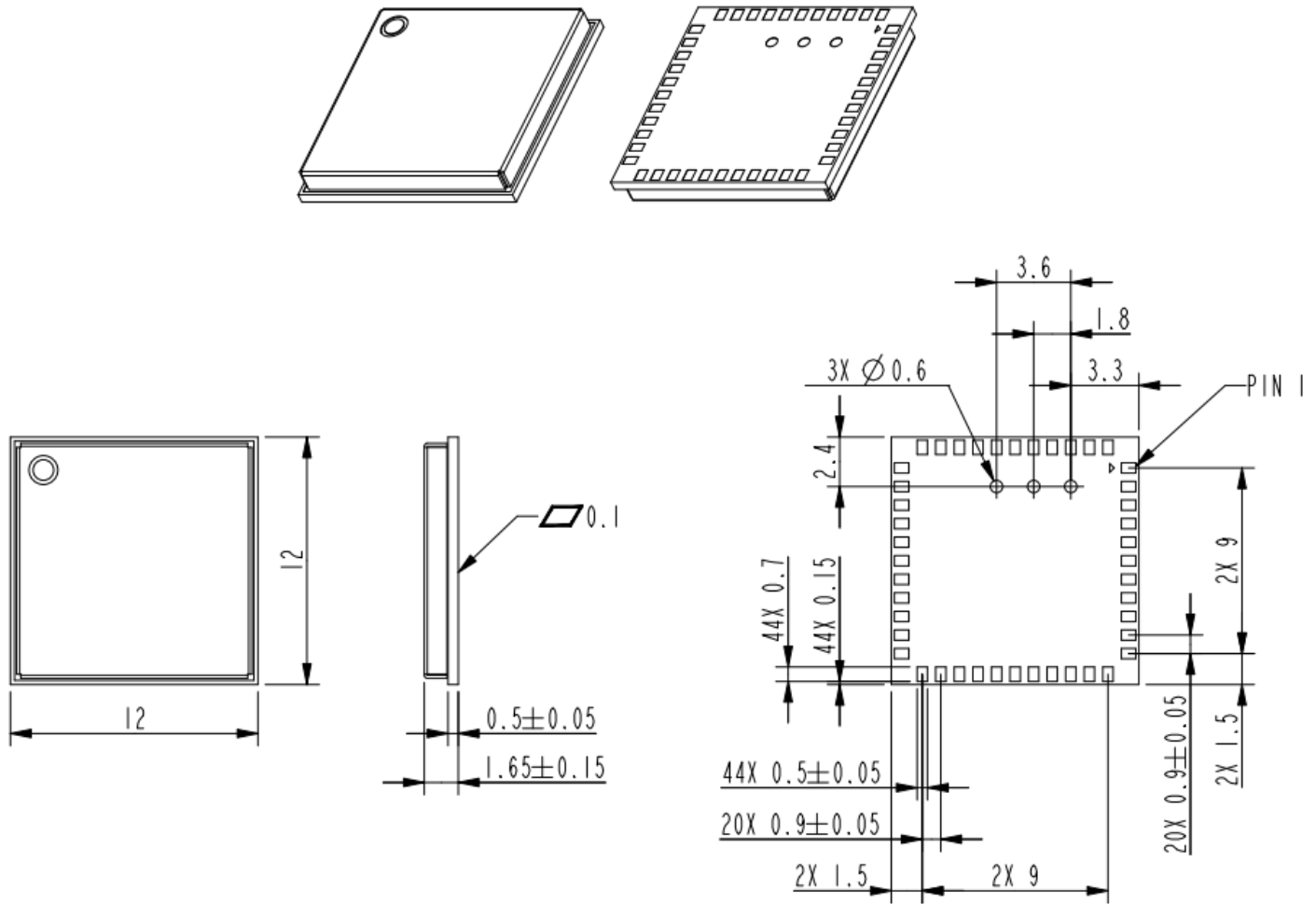
TBD

\* The power consumption is based on Azurewave test environment, these data for reference only.



## 4. Mechanical Information

### 4.1 Mechanical Drawing



TOLERANCE UNLESS OTHERWISE SPECIFIED:  $\pm 0.1$  mm

## 5. Packaging Information

TBD